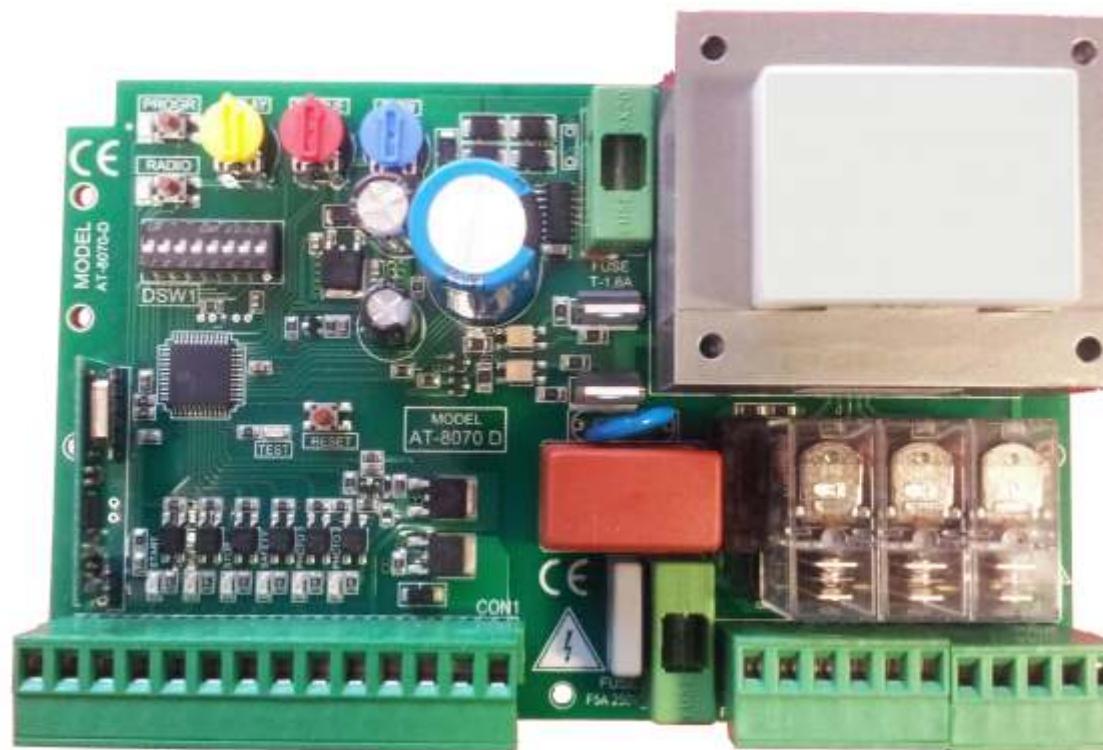


AT-8070-D

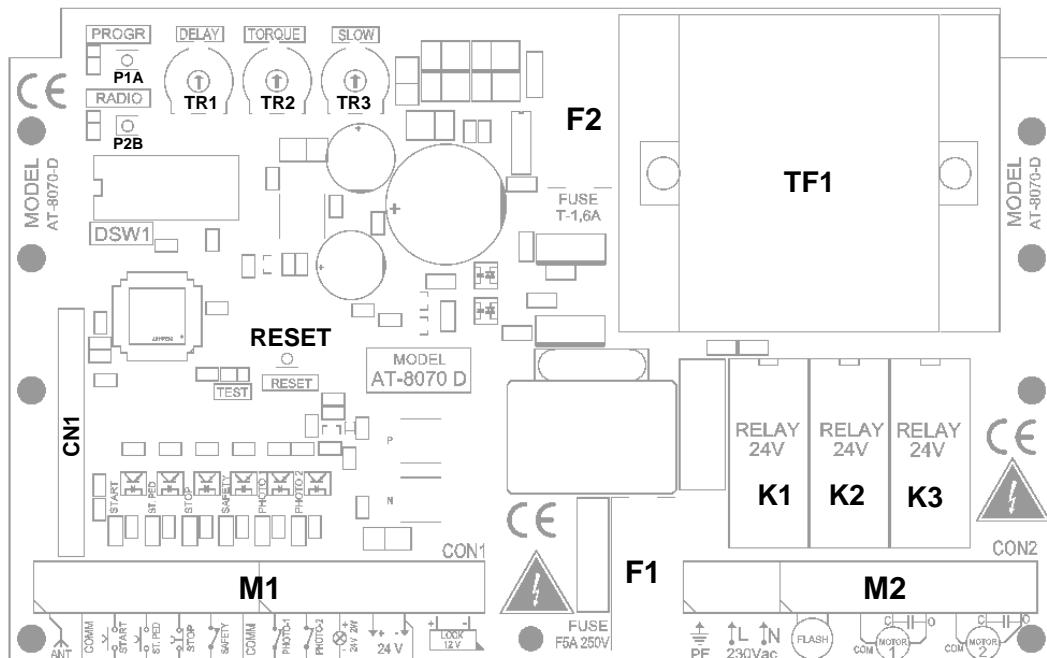
230 Vac



μ

AT-8070-D

P1A = $\mu\mu$ μ
P2B = $\mu\mu$ μ
DSW1 =
TR1, TR2, TR3 = μ trimmers
RESET = Reset μ
F2 = μ
TF1 = μ
CN1 =
M1 = μ - μ
F1 = 230Vac
M2 = μ - 230Vac
K1 – K3 =



-8070-D μ 300 W μ
 μ μ 650 W 230Vac 50Hz.
 μ μ μ μ μ
 μ μ μ μ μ
 μ μ μ μ 6 /30mA
 μ μ μ
 μ μ μ
 μ μ μ



Declaration of Conformity (No: 102)

We AutoTech Georgia Kapsali, Glonas 11, Peristeri, 12133, Athens, Greece,

declare under our sole responsibility that the product:

Name: Control board for swinging gates motor

Model: AT8070D

to which this declaration relates is in conformity with the essential requirements of:

- 2014/53/EU – Radio Equipment Directive (RED)
- 2011/65/EU – RoHS Directive
- 2012/19/EU – WEEE Directive

For the evaluation of the compliance with these Directives and Regulations, the following standards were applied:

SAFETY (article 3.1.a of RED)	EN 60950-1:2006+A11:2009+A1:2010+A12:2011+A2:2013 EN 60335-1:2012+A11:2014+A13:2017
HEALTH (article 3.1.a of RED)	EN 62479:2010
EMC (article 3.1.b of RED)	ETSI EN 303 446-1 V1.1.0 (2017-03)
SPECTRUM (article 3.2 of RED)	ETSI EN 300 220-1 V3.1.1 (2017-02) ETSI EN 300 220-2 V3.1.1 (2017-02)
RoHs	EN 50581:2012
WEEE	EN 50419:2006

NOTE: It is important that the product is subjected to a correct installation, use and maintenance, conforming to intended purpose, applicable regulations and standards, to supplier's instructions and user's manual.

Signed for and on behalf of: AutoTech Georgia Kapsali

Place and date of issue: Athens 28/10/2017

Name, function: Antonios Apergis

Signature:

230V 50Hz μ μ
 μ μ 24V. μ μ 0,5mm²
 μ μ μ μ μ 1,5mm²
 μ μ μ μ μ 230V 50Hz.
 μ μ μ μ μ 2,5 mm²

μ 1
 ANTENNA =
 COM =
 START = μ N.O. (μ / μ)
 ST.PED = μ N.O. (μ)
 STOP = μ N.C. (STOP)
 SAFETY = N.C.
 COM
 PHOTO1 = N.C.
 PHOTO2 = N.C.
 W. L GHT 2W 24V = 24Vdc 2W max.
 +24V = 24Vdc μ
 -24V = 24Vdc μ
 LOCK = 12Vac

μ 2
 PE =
 L = 230V 50Hz
 N = 230V 50Hz ()
 FLASH = 230V 50Hz 15 W max.
 Motor 1 COM = 1.
 Motor 1 C = μ 1.
 Motor 1 O = μ 1.
 Motor 2 COM = 2.
 Motor 2 C = μ 2.
 Motor 2 O = μ 2.

μμ M2 . N.C. μ μμ 1
 flasher μ μ μμ
 μ . (START S.TP) μ N.C. μ TEST_LED
 μ

CONDOMINIUM:

START μ START
 μ START μ μ STOP,
 μ

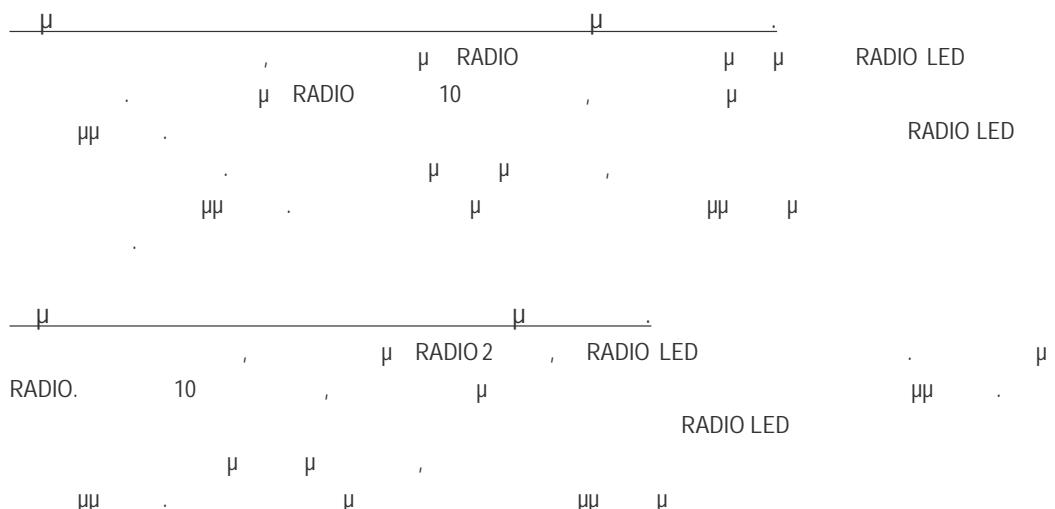
STEP BY STEP:

START μ START μ START,
 μ START μ μ START
 μ "μ μ 1,2,3 6,
 JR1 "μ). μ

DIP SWITCH

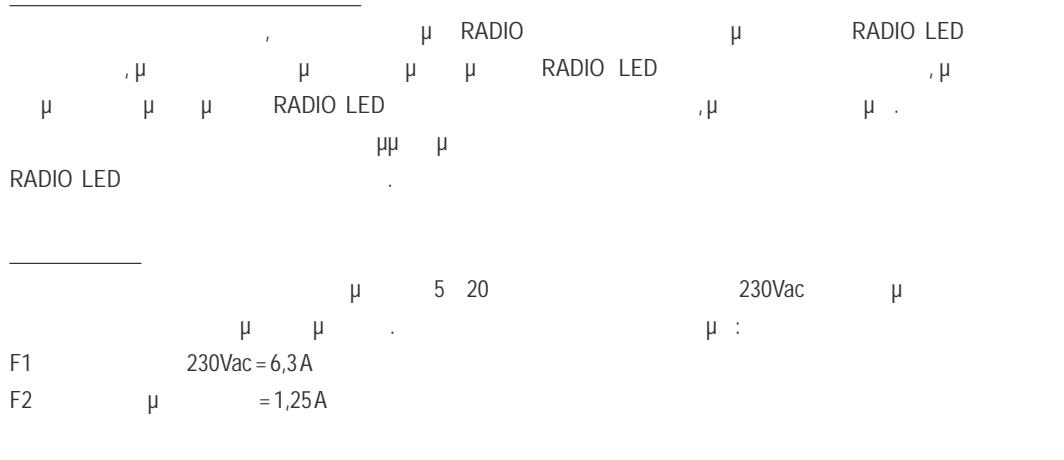
DIP-1	<input type="checkbox"/> On	Condominium
	<input type="checkbox"/> Off	Step By Step
DIP-2	<input type="checkbox"/> On	μ μ (Trimmer)
	<input type="checkbox"/> Off	μ μ
DIP-3	<input type="checkbox"/> On	μ μ μ (Normal)
	<input type="checkbox"/> Off	μ μ μ (Easy)
DIP-4	<input type="checkbox"/> On	Preflashing μ
	<input type="checkbox"/> Off	Preflashing μ

DIP-5	(μ)
DIP-6	On Retrigger	μ
	Off Retrigger	μ
DIP-7	On	μ
	Off	
DIP-8	μ	μ



TRIMMER

TR1	μ	μ	μ	(μ	μ	μ)
	μ	1	120	.			
TR2	μ				μ	μ	μ
					trimmer TR2	μ	μ
TR3	μ	μ	μ	.	μ	trimmer TR3	μ
					μ	(μ
					μ	μ	μ
).



Trimmer

TR1	μ	μ	1-120
TR2			20-100%
TR3			10-100%
			100% (
			μ
			μ
)

AT-8070-D

μ	128						
μ							

(Normal)

• μ trimmer TORQUE
 μ trimmer SLOW

• μ μ PROGR PROGR LED
 μ PROGR

START:

START:

START:

START:

START:

START:

START:

START:

START.

START:

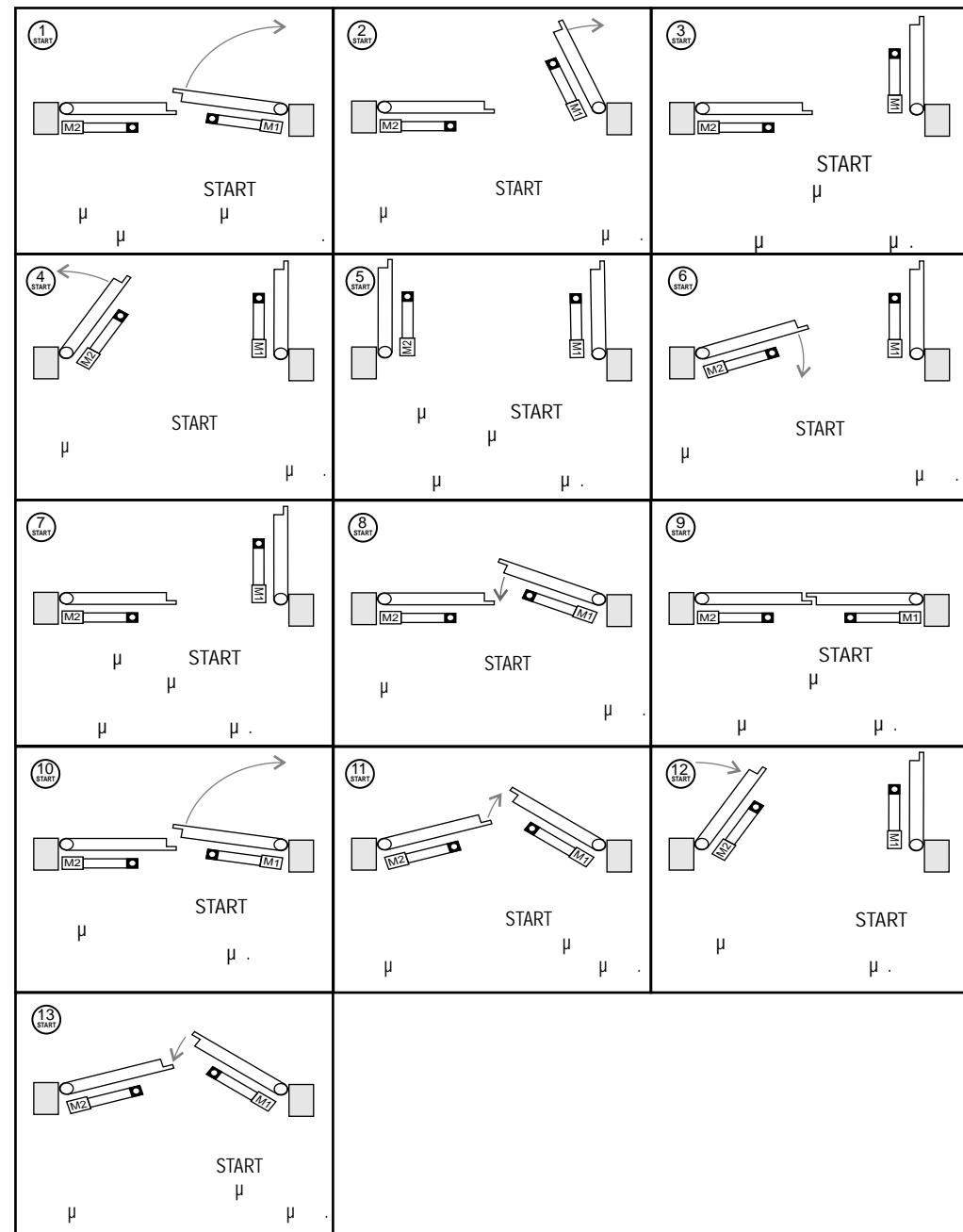
START:

μ μ PROGR LED

μ μ μ

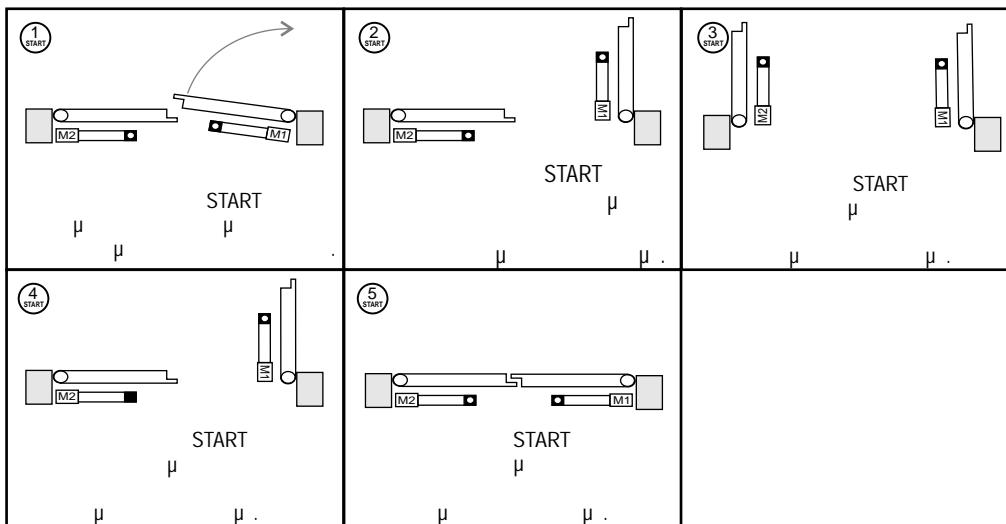
μ μ μ μ μ μ μ $\mu\mu$

RESET μ μ μ (12).



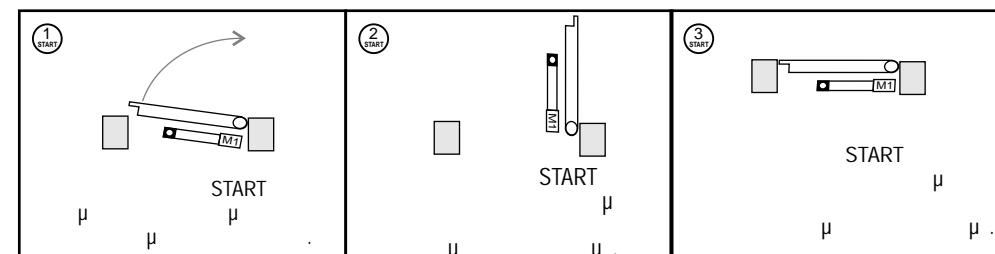
(Easy)

- μ trimmer TORQUE
 μ trimmer SLOW μ
- μ μ PROGR RPOGR LED
- μ PROGR
- START:
 START:
- START:
- START:
- START:
- START.
- μ μ PROGR LED
- μ μ μ
- μ 2 μ μ (4 sec.).
 (3 sec)
- μ RESET μ
 (12).

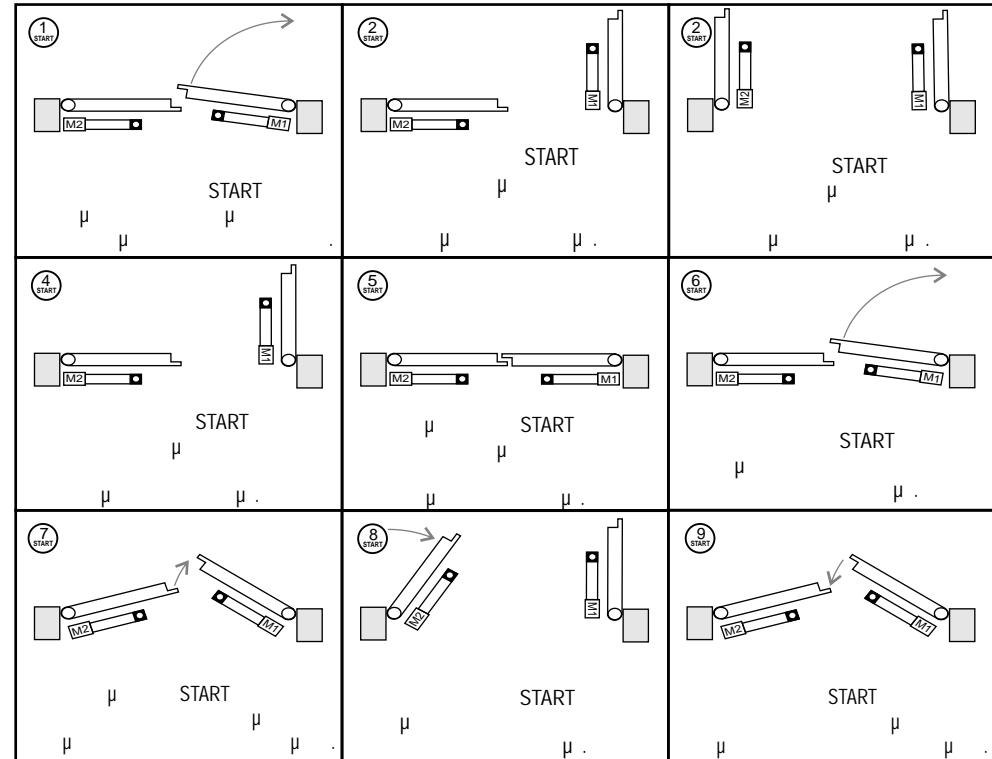


(Easy)

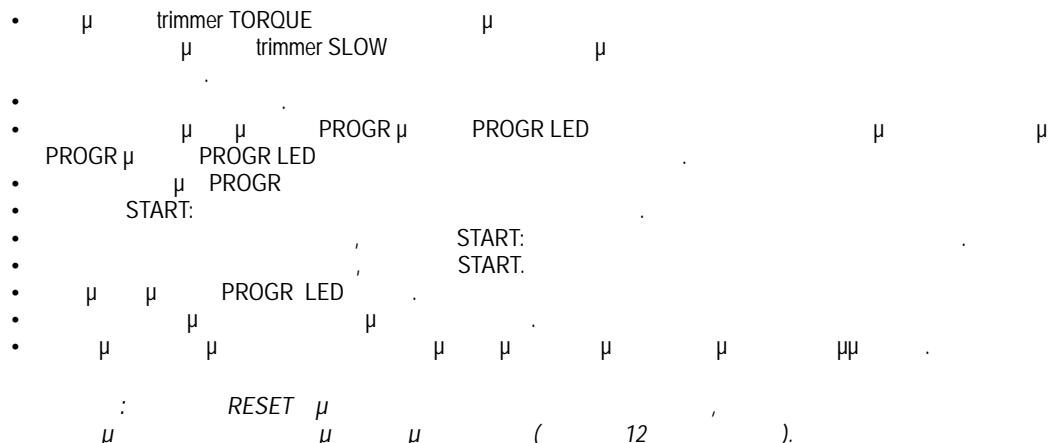
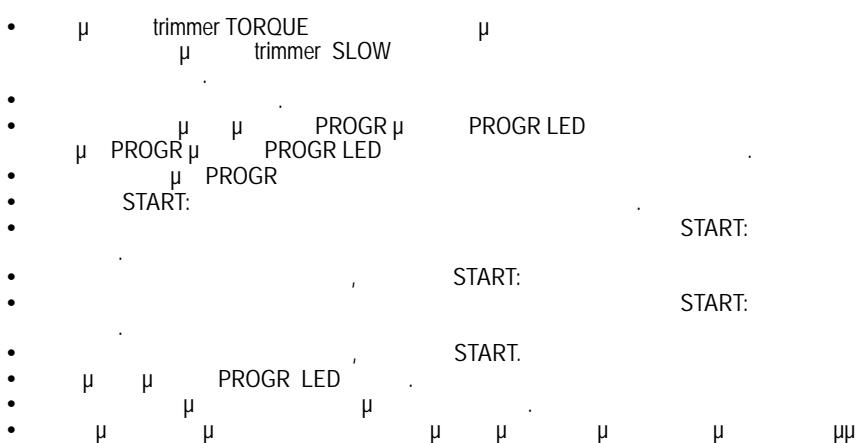
- μ trimmer TORQUE
 μ trimmer SLOW μ
- μ μ PROGR μ PROGR LED
- μ PROGR μ PROGR
- START:
 START:
 START:
- μ μ PROGR LED
 (3 sec).
- μ μ μ
- μ RESET μ
 (12).



• μ trimmer TORQUE
 • μ trimmer SLOW
 • μ μ PROGR LED
 • μ PROGR
 START:
 RESET μ μ μ (12).



(Normal)



RESET μ μ (μ 12 μ).

